INFOMAGR – Advanced Graphics

Jacco Bikker - November 2022 - February 2023

Lecture 3 - "Light Transport"

Welcome!

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survive = SurvivalProbability(dif

at3 factor = diffuse * INVPI; at weight = Mis2(directPdf, brdfPdf at cosThetaOut = dot(N, L);

E * ((weight * cosThetaOut) / directPdf)
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n = E * brdf * (dot(N, R) / pdf);

at3 brdf = SampleDiffuse(diffuse, N, r1, r2, &R, &c

(AXDEPTH)

v = true;

Today's Agenda:

- Introduction
- The Rendering Equation
- Light Transport



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(), N );
refl * E * diffuse;
= true;

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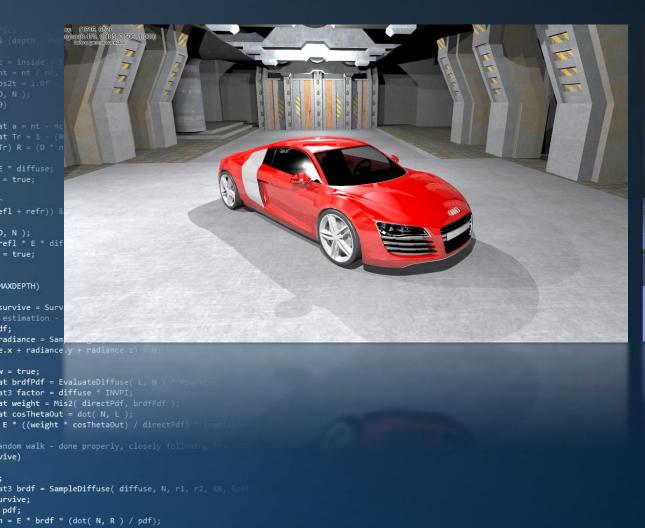
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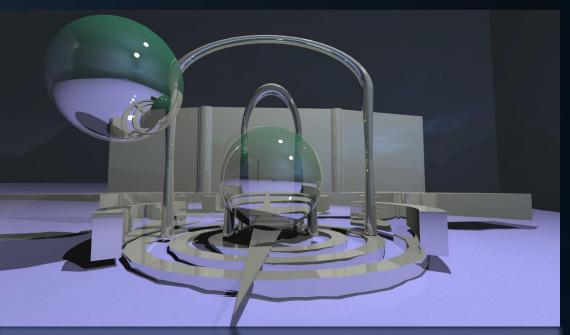
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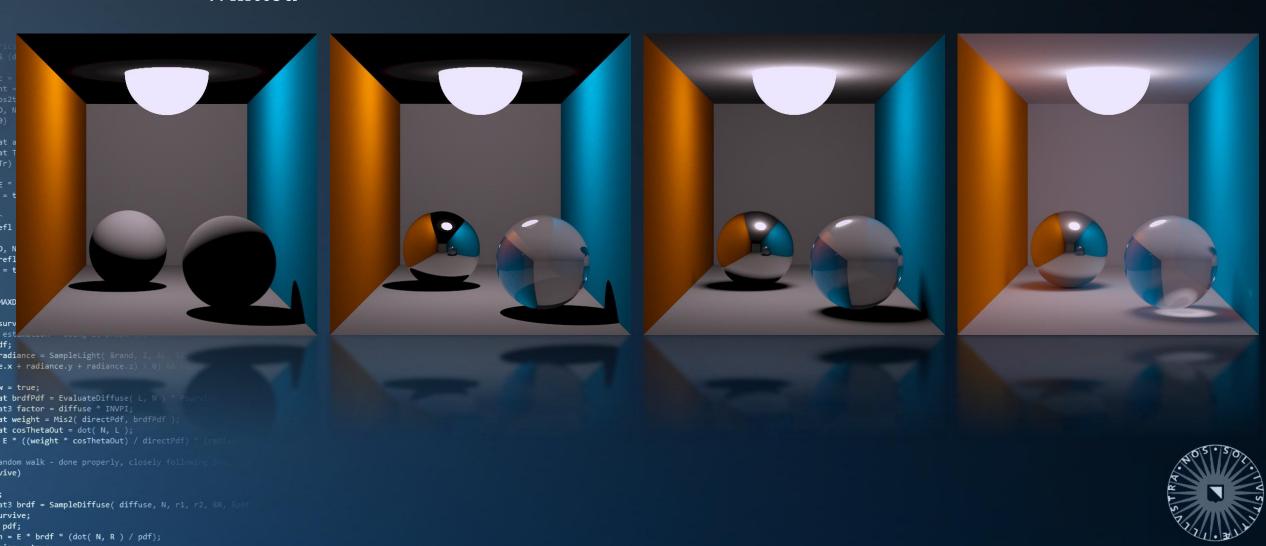
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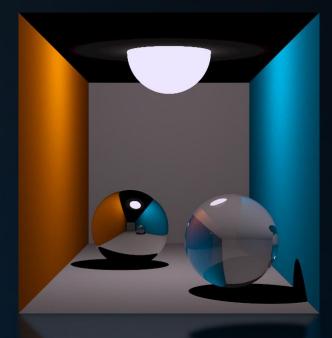
Whitted



Whitted

Missing:

- Area lights
- Glossy reflections
- Caustics
- Diffuse interreflections
- Diffraction
- Polarization
- Phosphorescence
- Temporal effects
- Motion blur
- Depth of field
- Anti-aliasing





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Anti-aliasing

Adding anti-aliasing to a Whitted-style ray tracer:

Send multiple primary rays through each pixel, and average their result.

Problem:

- How do we aim those rays?
- What if all rays return the same color?







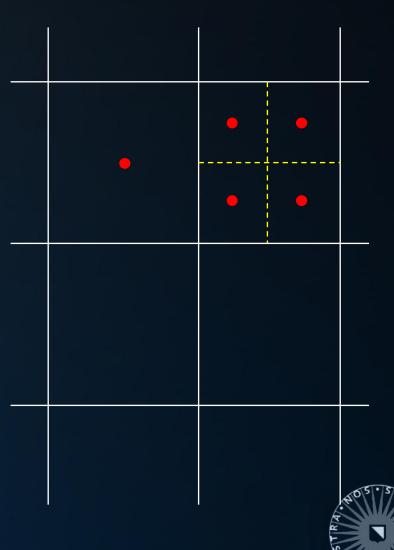
Anti-aliasing – Sampling Patterns

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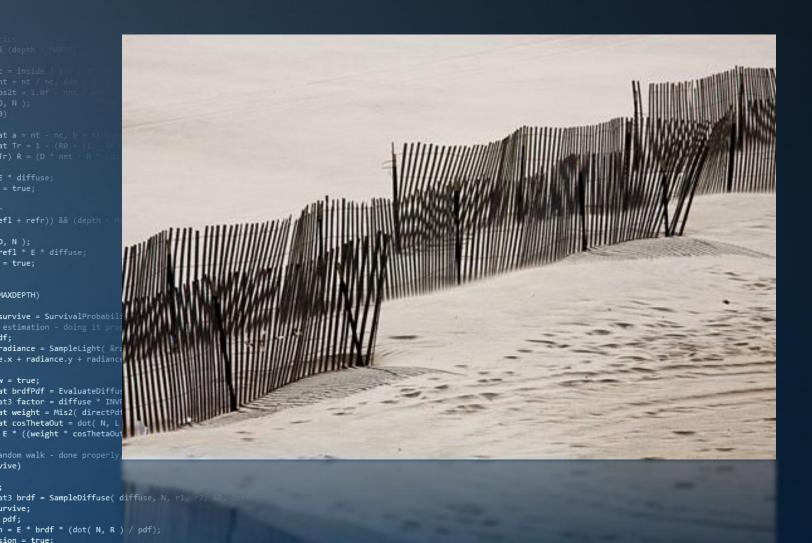
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Anti-aliasing – Sampling Patterns





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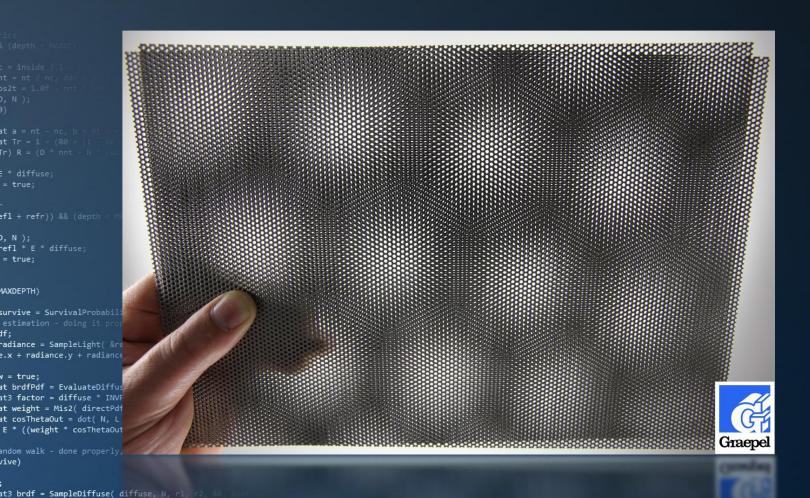
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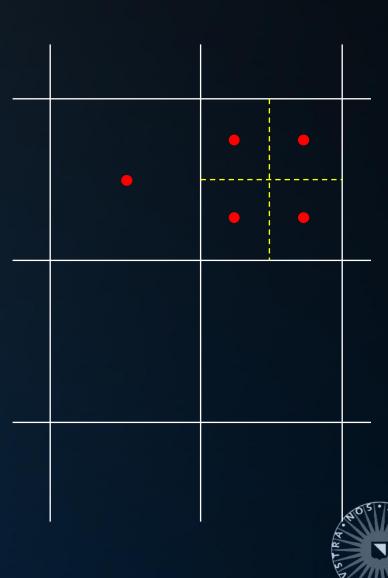
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More info: https://mynameismjp.wordpress.com/2012/10/24/msaa-overview

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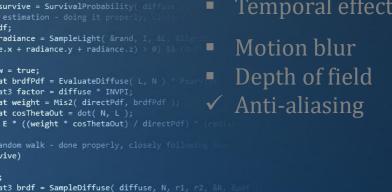
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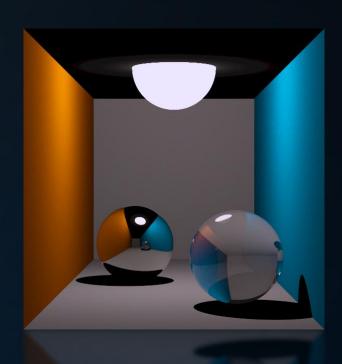
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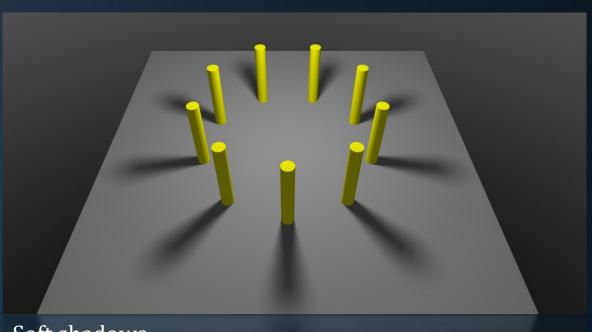




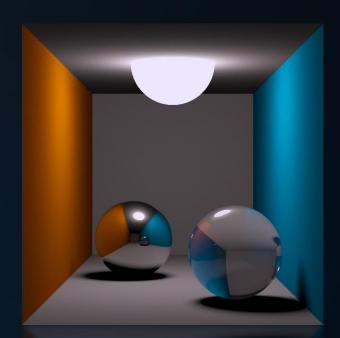


Distribution Ray Tracing*

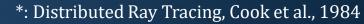
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E * ((weight * cosThetaOut) / directPdf)
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Soft shadows





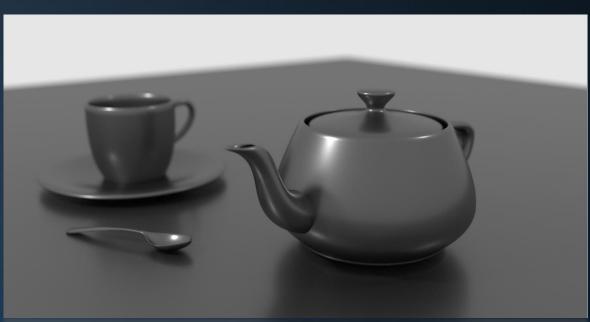


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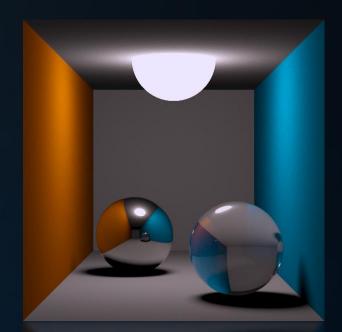


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Glossy reflections



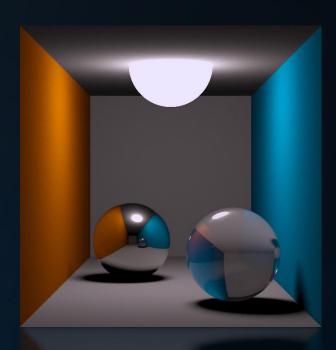


*: Distributed Ray Tracing, Cook et al., 1984

at3 brdf = SampleDiffuse(diffuse, N, r1, r2, &R, &pdf urvive; pdf; n = E * brdf * (dot(N, R) / pdf);

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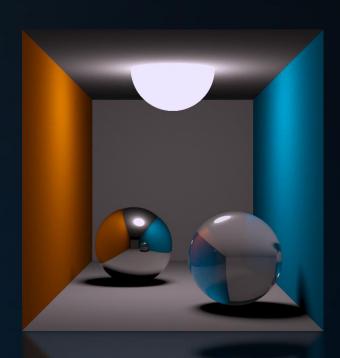
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pdf; n = E * brdf * (dot(N, R) / pdf);

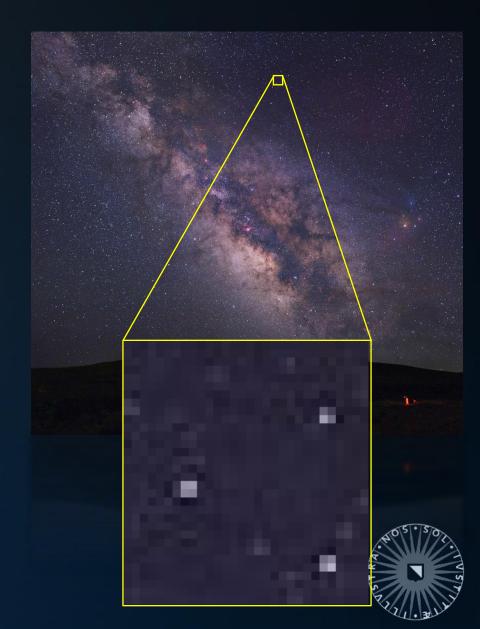
Distribution Ray Tracing

Whitted-style ray tracing is a *point sampling* algorithm:

- We may miss small features
- We cannot sample areas

Area sampling:

- Anti-aliasing: one pixel
- Soft shadows: one area light source
- Glossy reflection: directions in a cone
- Diffuse reflection: directions on the hemisphere



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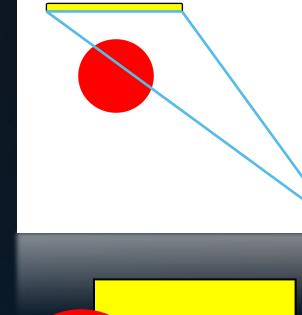
Area Lights

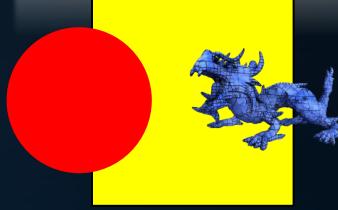
$$V_A = \int_A V(x, \omega_i) \, d\omega_i$$

$$V_A = A_{light} - A_{light \cap sphere}$$

Analytical solution case 2:

$$V_A = ?$$







Visibility of an area light source:

$$V_A = \int_{\mathbb{R}^n} V(x, \omega_i) d\omega_i$$

Analytical solution case 1:

$$V_A = A_{light} - A_{light \cap sphere}$$

Approximating Integrals

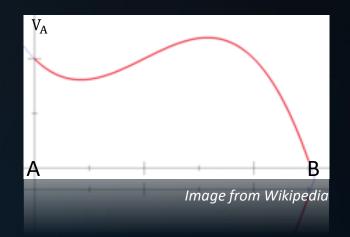
An integral can be approximated as a Riemann sum:

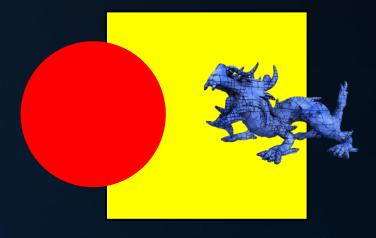
$$V_A = \int_A^B f(x) dx \approx \sum_{i=1}^N f(t_i) \Delta_i$$
, where $\sum_{i=1}^N \Delta_i = B - A$

Note that the intervals do not need to be uniform, as long as we sample the full interval. If the intervals are uniform, then

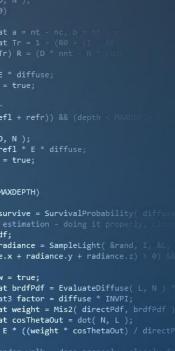
$$\sum_{i=1}^{N} f(t_i) \, \Delta_i = \Delta_i \sum_{i=1}^{N} f(t_i) = \frac{B - A}{N} \sum_{i=1}^{N} f(t_i).$$

Regardless of uniformity, restrictions apply to N when sampling multi-dimensional functions (ideally, $N = M^d$, $M \in \mathbb{N}$). Also note that aliasing may occur if the intervals are uniform.









at3 brdf = SampleDiffuse(diffuse, N, r1, r2, &R,)

1 = E * brdf * (dot(N, R) / pdf);

Monte Carlo Integration

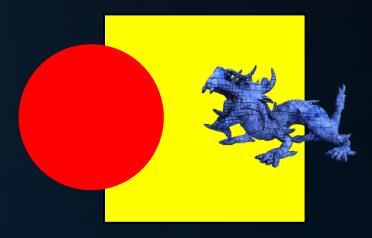
Alternatively, we can approximate an integral by taking random samples:

$$V_A = \int_A^B f(x) dx \approx \frac{B-A}{N} \sum_{i=1}^N f(X_i)$$

Here, $X_1 ... X_N \in [A, B]$.

As N approaches infinity, V_A approaches the *expected value* of f(X).

Unlike in Riemann sums, we can use arbitrary *N* for Monte Carlo integration, regardless of dimension.





at cosThetaOut = dot(N, L);

E * ((weight * cosThetaOut) / directPdf)
andom walk - done properly, closely follow

n = E * brdf * (dot(N, R) / pdf);

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Monte Carlo Integration of Area Light Visibility

To estimate the visibility of an area light source, we take *N* random point samples.

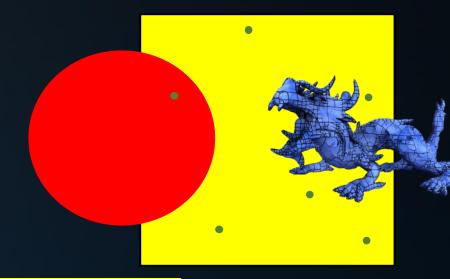
In this case, 5 out of 6 samples are unoccluded:

$$V \approx \frac{1}{6}(1+1+1+0+1+1) = \frac{5}{6}$$

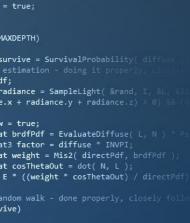
Properly formulated using a MC integrator:

$$V = \int_{S^2} V(p) dp \approx \frac{1}{N} \sum_{i=1}^{N} V(P)$$

With a small number of samples, the variance in the estimate shows up as noise in the image.



Q: Where did the $\frac{B-A}{N}$ go? A: the domain of the visibility function is [0..1], so B-A=1.



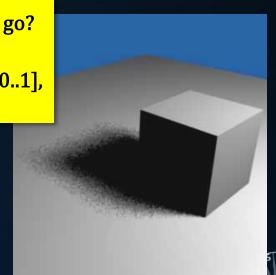
at3 brdf = SampleDiffuse(diffuse, N, r1, r2, &R, A

1 = E * brdf * (dot(N, R) / pdf);

efl + refr)) && (depth

refl * E * diffuse;

), N);



Distribution Ray Tracing

Key concept of distribution ray tracing:

We estimate integrals using Monte Carlo integration.

Integrals in rendering:

- Area of a pixel
- Lens area (aperture)
- Frame time
- Light source area
- Cones for glossy reflections
- Wavelengths
- Many lights







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- The Rendering Equation
- Light Transport



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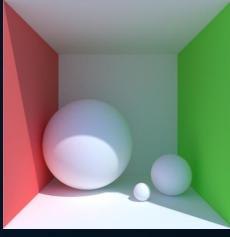
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- Motion blur
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Cook:

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survive = SurvivalProbability(di

radiance = SampleLight(&rand, I,

.x + radiance.y + radiance.z) > 0

at weight = Mis2(directPdf, brdfPdf at cosThetaOut = dot(N, L);

E * ((weight * cosThetaOut) / directPdf)
andom walk - done properly, closely follo

refl * E * diffuse;

), N);

= true;

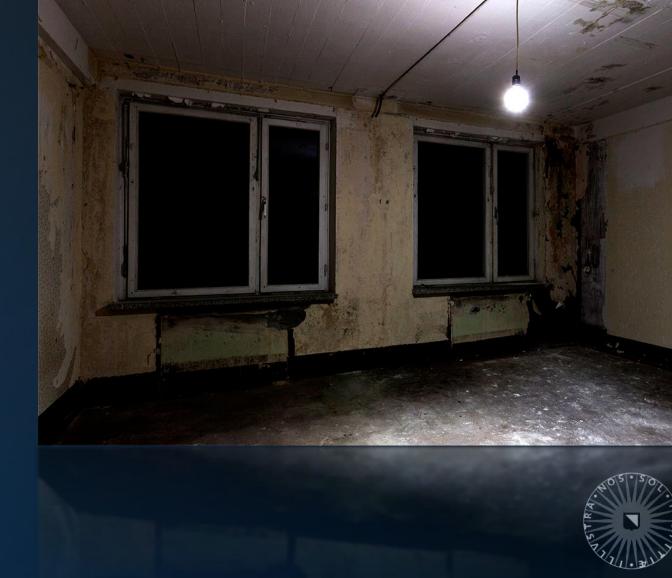
(AXDEPTH)

God's Algorithm

1 room
1 bulb
100 watts
10²⁰ photons per second

Photon behavior:

- Travel in straight lines
- Get absorbed, or change direction:
 - Bounce (random / deterministic)
 - Get transmitted
- Leave into the void
- Get detected



eff + refr)) && (depth < MAXDEFIN

(a), N);

ref1 * E * diffuse;

= true;

MAXDEPTH)

Survive = SurvivalProbability(diffuse | estimation - doing it properly, classed | fif;

radiance = SampleLight(&rand, I, &L, &lighter | e.x + radiance.y + radiance.z) > 0) && (detail | e.x + radiance.y + radiance.z) > 0) && (detail | e.x + radiance.y + radiance.z) > 0) && (detail | e.x + radiance.y + radiance.z) > 0) && (detail | e.x + radiance.y + radiance.z) > 0) && (detail | e.x + radiance.y + radiance.z) > 0) && (detail | e.x + radiance.y + radiance.z) > 0) && (detail | e.x + radiance.y + radiance.z) > 0) && (detail | e.x + radiance.y + radiance.z) > 0) && (detail | e.x + radiance.y + radiance.z) > 0) && (detail | e.x + radiance.y + radiance.z) > 0) && (detail | e.x + radiance.y + radiance.z) > 0) && (detail | e.x + radiance.y + radiance.z) > 0) && (detail | e.x + radiance.z) > 0) && (detai

1 = E * brdf * (dot(N, R) / pdf);

pdf; n = E * brdf * (dot(N, R) / pdf);

Rendering Equation D, N); refl * E * diffuse; (AXDEPTH) survive = SurvivalProbability(diff) radiance = SampleLight(&rand, I, &L, & e.x + radiance.y + radiance.z) > 0) &a v = true; at brdfPdf = EvaluateDiffuse(L, N) at3 factor = diffuse * INVPI; at weight = Mis2(directPdf, brdfPdf); at cosThetaOut = dot(N, L); E * ((weight * cosThetaOut) / directPdf) at3 brdf = SampleDiffuse(diffuse, N, r1, r2, &R, ırvive;

at3 brdf = SampleDiffuse(diffuse, N, r1, r2, &

1 = E * brdf * (dot(N, R) / pdf);

God's Algorithm - Mathematically

A photon may arrive at a sensor after travelling in a straight line from a light source to the sensor:

$$L(s \leftarrow x) = L_E(s \leftarrow x)$$

Or, it may be reflected by a surface towards the sensor:

$$L(s \leftarrow x) = \int_A f_r(s \leftarrow x \leftarrow x') L(x \leftarrow x') G(x \leftrightarrow x') dA(x')$$

Those are the options.

Adding direct and indirect illumination together:

$$L(s \leftarrow x) = L_E(s \leftarrow x) + \int_A f_r(s \leftarrow x \leftarrow x') L(x \leftarrow x') G(x \leftrightarrow x') dA(x')$$





God's Algorithm - Mathematically

Emission

```
efl + refr)) && (depth
), N );
refl * E * diffuse;
= true;
(AXDEPTH)
survive = SurvivalProbability( diff
radiance = SampleLight( &rand, I, &L
e.x + radiance.y + radiance.z) > 0)
v = true;
at brdfPdf = EvaluateDiffuse( L, N )
at3 factor = diffuse * INVPI
at weight = Mis2( directPdf, brdfPdf )
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf)
andom walk - done properly, closely follow
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &p
1 = E * brdf * (dot( N, R ) / pdf);
```

```
L(s \leftarrow x) = L_E(s \leftarrow x) + \int_A f_r(s \leftarrow x \leftarrow x') \ L(x \leftarrow x') \ G(x \leftrightarrow x') \ dA(x') Geometry factor Indirect Reflection Hemisphere
```





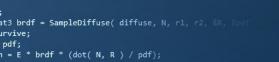
$$L(s \leftarrow x) = L_E(s \leftarrow x) + \int_A f_r(s \leftarrow x \leftarrow x') L(x \leftarrow x') G(x \leftrightarrow x') dA(x')$$

The Rendering Equation*:

- Light transport from lights to sensor
- Recursive
- Physically based

The equation allows us to determine to which extend rendering algorithms approximate real-world light transport.

*: The Rendering Equation, Kajiya, 1986



efl + refr)) && (dept)

survive = SurvivalProbability(

radiance = SampleLight(&rand, I, . e.x + radiance.y + radiance.z) <u>> 0</u>

at brdfPdf = EvaluateDiffuse(L, N)
at3 factor = diffuse * INVPI;
at weight = Mis2(directPdf, brdfPdf
at cosThetaOut = dot(N, L);

E * ((weight * cosThetaOut) / directPdf)

refl * E * diffuse;

(AXDEPTH)



Today's Agenda:

- Introduction
- The Rendering Equation
- Light Transport



```
refl + refr)) && (depth < MAXDEPHH)

(), N );
refl * E * diffuse;
= true;

MAXDEPTH)

survive = SurvivalProbability( diffuse :
estimation - doing it properly, closes

ff;
radiance = SampleLight( &rand, I, &L, &lightener
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ex.x + radiance.y + radian
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Today's Agenda:

- Introduction
- The Rendering Equation
- Light Transport



```
refl + refr)) && (depth < MAXDEPHH)

(), N );
refl * E * diffuse;
= true;

MAXDEPTH)

survive = SurvivalProbability( diffuse :
estimation - doing it properly, closes

ff;
radiance = SampleLight( &rand, I, &L, &lightener
ex.x + radiance.y + radiance.z) > 0) && (details

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ex.x + radiance.y + radiance.z) > 0) && (details

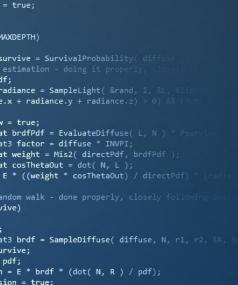
ex.x + radiance.y + radian
```

INFOMAGR – Advanced Graphics

Jacco Bikker - November 2022 - February 2023

END of "Light Transport"

next lecture: "Path Tracing"



efl + refr)) && (depth < M

refl * E * diffuse;

), N);

